Voltage Drop, Potential Difference and $\mathcal{E}M\mathcal{F}$

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1 Introduction

To give the concept of voltage a well-defined meaning in time-dependent electromagnetism,¹ we advocate that it be defined as the retarded electric scalar potential [2, 3, 4] in the Lorenz gauge [5] (plus a possible additive constant),

$$V(r, t) = \int \frac{\rho(r', t' = t - R/c)}{4\pi \epsilon_0 R} d\text{Vol}' \quad \text{(Lorenz),}$$

in SI units, where $\rho$ is the electric charge density, $c$ is the speed of light in the medium between $r$ and $r'$ (assumed in this note to be vacuum), $R = |r - r'|$, and $\epsilon_0$ is the permittivity of the vacuum. This convention follows Stratton [6], p. 352.²

A prominent application of the notion of voltage is in circuit analysis, where prescriptions exist for the “voltage drop” across various circuit elements (secs. 3.2.1-5), and where Kirchhoff’s (voltage) law states that the sum of the “voltage drops” around any loop is zero. However, Kirchhoff’s “law” is only approximately valid, and the “voltage drops” it considers are, in general, neither differences in the electric scalar potential $V$, nor the $\mathcal{E}M\mathcal{F} = \int \mathbf{E} \cdot d\mathbf{l}$ along some path between the ends of the circuit element.³

In “ordinary” circuit analysis, as defined below, the “voltage drops” are well approximated by both the difference in the electric scalar potential (in the Lorenz gauge) and by the $\mathcal{E}M\mathcal{F}$ along a suitable path. But, great care is required when considering examples outside “ordinary” circuit analysis where these familiar approximations can be very poor (sec. 3.4).

An “ordinary” circuit, operating at angular frequency $\omega$, is a circuit for which:⁴

1. The size of the circuit is small compared to the wavelength $\lambda = 2\pi c/\omega$. In this case there is no spatial variation to the current in any segment of a loop between two nodes;

2. Effects of retardation (wave propagation) and radiation (flow or energy into or out of the circuit via the electromagnetic field [9] can be ignored;⁵

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¹The ambiguous meaning of “voltage” is noted, for example, in [1].

²In contrast, some authors consider that voltage is undefined outside electrostatics [7].

³Kirchhoff’s (circuit loop) law is often considered to be equivalent to conservation of energy, with $q\Delta V = q \int \mathbf{E} \cdot d\mathbf{l}$ being the work done by the electric field on a charge $q$ that moves along a segment of a circuit loop. In this context, the magnetic field $\mathbf{B}$ does no work [8]. However, the energy of the charges is conserved only if the circuit elements remain at rest, and radiation is ignored.

⁴A superconducting loop, for which $\oint \mathbf{E} \cdot d\mathbf{l} = 0 = -d\Phi_M/dt$, is not an “ordinary” circuit, as the magnetic flux $\Phi_M$ and current $I$ cannot change (without resulting in a “quench” in which the conductor goes “normal”). A circuit that is partly superconducting can be an “ordinary” circuit if it meets the three criteria above.

⁵When retardation is ignored the Lorenz-gauge scalar potential reduces to the (instantaneous) Coulomb potential. Hence, the conceptual preference for the Lorenz-gauge potentials over those in the Coulomb gauge becomes apparent only in situations in which retardation and wave propagation are significant (sec. 3.3).
3. Magnetic flux through the circuit is well localized in small inductors (coils).

4. All circuit elements are at rest.  

The vast success of circuit analysis leaves many people with the impression that it is an “exact” procedure, which results in considerable confusion in the realms where the approximations of “ordinary” circuit analysis are not valid (transmission lines, antennas, and even “simple” circuits where the self inductance of a loop cannot be neglected, etc.). This has led to the unfortunate impression that “voltage” is ill defined, or irrelevant, in examples outside “ordinary” circuit analysis. The present note attempts to provide some correction to this misapprehension.

2 Electrostatics

The concept of voltage $V$ is well defined (up to an additive constant) in electrostatics, where it is identified with the electrostatic Coulomb potential $\phi$, and also with the $\mathcal{EMF}$ (electromotive force),

$$V(r) - V_0 = \phi(r) - \phi(r_0) = -\mathcal{EMF}(r_0, r) \quad \text{(electrostatics),}$$

where $V_0$ is the voltage at the reference position $r_0$, the Coulomb potential is

$$\phi(r) = \int \frac{\rho(r')}{4\pi \epsilon_0 R} dV' \quad \text{(Coulomb),}$$

$\rho$ is the (static) electric charge density, the electromotive force is

$$\mathcal{EMF}(r_0, r) = \int_{r_0}^r \mathbf{E} \cdot dl \quad \text{(electrostatics),}$$

and the electric field $\mathbf{E}$ is related to the potential $\phi$ by

$$\mathbf{E} = -\nabla \phi.$$  

The $\mathcal{EMF}$ is a unique function of $r_0$ and $r$, independent of the path of integration, only if $\nabla \times \mathbf{E} = 0$. This condition does hold in electrostatics (and magnetostatics). Furthermore, the energy stored in the electric field of an electric charge $Q$ at rest and a static electric charge density $\rho$ (not including $Q$) is

$$U_E = Q \phi(r_Q) = Q \int \frac{\rho(r')}{4\pi \epsilon_0 R} dV' \quad \text{(electrostatic),}$$

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6When circuit elements are in motion, Faraday’s law is often invoked to consider them as effective sources of $\mathcal{EMF}$, but care is needed in doing so. See, for example, sec. 17-2 of [10]. We do not pursue this topic further here; for an example by the author, see [11].

7A static electric field obeys $\partial \mathbf{E} / \partial t = 0$, in which case the magnetic field $\mathbf{B}$ obeys $\partial^2 \mathbf{B} / \partial t^2 = 0$, as follows on taking the time derivative of Faraday’s law, $\nabla \times \mathbf{E} = -\partial \mathbf{B} / \partial t$. In principle, this is consistent with a magnetic field that varies linearly with time, $\mathbf{B}(r, t) = \mathbf{B}_0(r) + \mathbf{B}_1(r)t$. However, this leads to arbitrarily large magnetic fields at early and late times, and nonzero $\mathbf{B}_1$ is excluded on physical grounds. Hence, $\partial \mathbf{E} / \partial t = 0$ implies that $\partial \mathbf{B} / \partial t = 0$ also, and $\nabla \times \mathbf{E} = 0$ according to Faraday’s law. However, the condition that $\nabla \times \mathbf{E} = 0$ does not necessarily imply that $\partial \mathbf{E} / \partial t = 0$. See, for example, [12].
where $R$ is the distance between the charge $Q$ (at $r_Q$) and the volume element at $r'$, so the static Coulomb potential $\phi(r)$ can also be interpreted as the electrostatic energy of a unit test charge at $r$ and the charge distribution $\rho$.

The concept of voltage has found great popular appeal in electrostatics as characterizing the $\mathcal{E}\mathcal{M}\mathcal{F}$ of batteries, and in Ohm’s law,

$$\Delta V = IR$$

where $\Delta V$ is the “voltage drop” across a resistor $R$ that carries a steady current $I$.

The term "high voltage" is often associated with the possibility of electrical “breakdown” via sparks in an otherwise static situation. However, this phenomenon is more properly associated with high electric field (= high voltage gradient in a static situation).

3 Electrodynamics

The simplicity of the relations (2) does not carry over to time-dependent electrodynamics where $\nabla \times \mathbf{E} = -\partial \mathbf{B} / \partial t \neq 0$, and the $\mathcal{E}\mathcal{M}\mathcal{F}$ (4) depends on the path between the end points of the line integral. The electric field cannot be deduced only from a scalar potential (called $V$ hereafter), but rather

$$\mathbf{E} = -\nabla V - \frac{\partial \mathbf{A}}{\partial t},$$

where $\mathbf{A}$ is the vector potential, which is related to the magnetic field by

$$\mathbf{B} = \nabla \times \mathbf{A}.$$  \hfill (9)

Also, the (time-dependent) energy stored in the electric field can be identified as$^8$

$$U_E = \frac{\varepsilon_0}{2} \int E^2 \, d\text{Vol} = \frac{1}{2} \int \rho V \, d\text{Vol} - \frac{\varepsilon_0}{2} \int V \frac{\partial \nabla \cdot \mathbf{A}}{\partial t} \, d\text{Vol} + \frac{\varepsilon_0}{2} \int \frac{\partial \mathbf{A}}{\partial t} \cdot \frac{\partial \mathbf{A}}{\partial t} \, d\text{Vol},$$

using eq. (8) to eliminate the electric field $\mathbf{E}$ in favor of the potentials $V$ and $\mathbf{A}$. Clearly, the “electrical” energy $U_E$ can no longer be related only to the scalar potential $V$.

The potentials $V$ and $\mathbf{A}$ in electrodynamics can have many forms, related by so-called gauge transformations that leave the fields $\mathbf{E}$ and $\mathbf{B}$ invariant [5, 13]. For example, we could set the scalar potential $V$ to zero, as first advocated by Gibbs [30, 31].$^9$

Alternatively, we could continue to identify the scalar potential $V$ with the instantaneous Coulomb potential (3); this option (for which $\nabla \cdot \mathbf{A} = 0$) has technical appeal mainly in situations where the charge density in quasistatic and propagation effects related to charges (in contrast to those of currents) are negligible.

$^8$If the energy stored in electrically polarized atoms is included in the “electrical” energy we have that $U_E = \int \mathbf{E} \cdot \mathbf{D} \, d\text{Vol}/2$.

$^9$A static electric field (with zero magnetic field) can be deduced via eq. (8) from the trivial vector potential $\mathbf{A}_{\text{Gibbs}} = -\mathbf{E} t$. See sec. VIII of [13] for a general expression for $\mathbf{A}$ in the gauge where $V = 0$. 3
In cases where wave propagation is significant it is appealing to use potentials that exhibit wave effects similar to those of the fields $E$ and $B$. This leads to use of the so-called Lorenz-gauge condition

$$\nabla \cdot A = -\frac{1}{c^2} \frac{\partial V}{\partial t} \quad \text{(Lorenz),}$$

and to the retarded potentials (1) and

$$A(r, t) = \frac{\mu_0}{4\pi} \int \frac{J(r', t' = t - \frac{R}{c})}{R} \, dV' \quad \text{(Lorenz),}$$

where $J$ is the electrical current density, and $\mu_0$ is the permeability of the vacuum.

The retarded scalar potential (1) is well-defined throughout all space, reduces to the Coulomb potential (3) in static situations, and in quasistatic situations, such as “ordinary” circuit analysis (defined in sec. 1), leads to “voltage drops” in good agreement with the approximations associated with the concepts of capacitors and inductors. We therefore advocate that the best generalization of the concept of voltage from electrostatics to electrodynamics is to consider the retarded scalar potential (1) to be the “voltage.”

### 3.1 Voltage, Voltage Sources, and Voltmeters

In many practical situations the notion of “voltage” is related to a “voltage source” which has an internal feedback systems designed to deliver a specific value of “voltage” across a pair of terminals, where that “voltage” is measured by a (built-in) voltmeter. This leads many people to consider that “voltage is what is measured by a voltmeter.”

So, what is a voltmeter, and what does it measure?\(^{10}\)

#### 3.1.1 Voltmeters

An (AC) voltmeter is an ammeter that measures the (oscillating) current $I_0$ that flows through a high-value resistor $R_0$ that is attached to leads whose tips, 1 and 2, may be connected to some other electrical system. The reading of the voltmeter (if properly calibrated) is $V_{\text{meter}} = I_0 (R_0 + R_{\text{leads}})$ where $R_{\text{leads}} \ll R_0. \quad ^{11}$

![Diagram](image)

In the approximation that the current does not vary spatially along the leads, the meter reading equals the $\mathcal{E}\mathcal{M}\mathcal{F}$ along the path of its conductors,

$$V_{\text{meter}} \approx \mathcal{E}\mathcal{M}\mathcal{F}_{\text{meter}} = \int_1^2 \mathbf{E} \cdot d\mathbf{l} = V_1 - V_2 - \frac{d}{dt} \int_1^2 \mathbf{A} \cdot d\mathbf{l} \quad \text{(along meter leads),} \quad (13)$$

\(^{10}\)This issue has a long history in pedagogic lore, [14, 15, 16, 17, 18, 19, 20, 21, 22, 23, 24, 25, 26, 27, 28, 29].

\(^{11}\)AC voltmeters often report the root-mean-square voltage $V_{\text{rms}} = I_0 (R_0 + R_{\text{leads}})/\sqrt{2}$ rather than $I_0 (R_0 + R_{\text{leads}})$. 

4
To see this, note that for a cylindrical, resistive medium of length \( l \), radius \( r \), and electrical conductivity \( \sigma \) that obeys Ohm’s law \( \mathbf{J} = \sigma \mathbf{E} \), where \( \mathbf{J} = I \hat{I}/\pi r^2 \) and \( I \) is the (uniform) axial current, then \( E l = Jl/\sigma = I l/\pi r^2 \sigma = IR \), and the (axial) electrical resistance is \( R = l/\pi r^2 \sigma \).

In time-varying situations, particularly where there are large magnetic fields in the vicinity of the circuit that is being probed by the voltmeter, the \( \mathcal{E}\mathcal{M}\mathcal{F} \) depends on the path between points 1 and 2. However, in “ordinary” circuits (ones that satisfy the three conditions given in sec. 1) there is very little magnetic flux linked by the loop that includes the voltmeter,\(^{12}\)

\[
0 \approx \Phi_M = \oint \mathbf{B} \cdot d \text{Area} = \oint_1^2 \mathbf{A} \cdot d \mathbf{l} + \oint_2^1 \mathbf{A} \cdot d \mathbf{l} \approx \oint_1^2 \mathbf{A} \cdot d \mathbf{l} \quad \text{(along meter leads), (14)}
\]

and the integral \( \oint_1^2 \mathbf{A} \cdot d \mathbf{l} \) is small (in the Lorenz gauge). This means that for such “ordinary” circuits the electric field between points 1 and 2 can be related to a scalar potential \( V \) according to \( \mathbf{E} \approx -\nabla V \) to a good approximation, such that

\[
\int_1^2 \mathbf{E} \cdot d \mathbf{l} \approx -\int_1^2 \nabla V \cdot d \mathbf{l} = V_1 - V_2. \quad \text{(15)}
\]

That is, when an AC voltmeter is used with an “ordinary” circuit it reads, to a good approximation, the voltage drop \( V_1 - V_2 \) between the electric scalar potential (in the Lorenz gauge) at the tips of its leads.\(^{13}\)

### 3.1.2 Voltage Sources

Following the above discussion, we see that a voltage source which is regulated by an internal voltmeter delivers a fixed \( \mathcal{E}\mathcal{M}\mathcal{F} \) to the extent that time-varying magnetic fields have negligible effect on the device. When such fields are negligible, the voltage source also delivers, to a good approximation, a fixed difference in the electric scalar potential (in the Lorenz gauge) between its terminals.

### 3.2 Voltage and AC Circuit Analysis

Circuit analysis is a mathematical model of a network of electrical components, such as “voltage” sources (DC or AC), wires (resistive or perfectly conducting), capacitors, inductors, as well as “active” devices such as diodes and transistors. A key assumption is that a scalar “voltage” can be assigned to each node of the network, and that there is a viable model for the “voltage drop” between any pair of nodes. An implication of this assumption is that the sum of the “voltage drops” is zero around any loop in the network/circuit.

Faraday’s law tells us that the line integral of the tangential electric field around a loop is non zero when the magnetic flux through the loop is time dependent,

\[
\mathcal{E}\mathcal{M}\mathcal{F}_{\text{loop}} = \oint \mathbf{E} \cdot d \mathbf{l} = -\frac{d \Phi_M}{dt} = -\frac{d}{dt} \oint \mathbf{B} \cdot d \text{Area} = -\frac{d}{dt} \oint \mathbf{A} \cdot d \mathbf{l}. \quad \text{(16)}
\]

\(^{12}\)If the loop includes an inductor we take the loop to follow a direct path between its ends, rather than following the winding. Very little magnetic flux is linked by the loop that includes this path, as discussed in sec. 3.2.1.

\(^{13}\)Discussion by the author of cases when a voltmeter does not read the difference in the electric scalar potential between its tips and/or the \( \mathcal{E}\mathcal{M}\mathcal{F} \oint \mathbf{E} \cdot d \mathbf{l} \) are given in [32, 33], which include many references to comments by others on this theme.
Hence, $\mathcal{E}\mathcal{M}\mathcal{F}$’s (line integral of the tangential electric field along some path) cannot strictly be the “voltage drops” used in AC circuit analysis, although it appears that most people identify “voltage” with $\mathcal{E}\mathcal{M}\mathcal{F}$ in circuit analysis.

In contrast, the electric scalar potential $V$ is a scalar defined at every point (once a “gauge” is specified), and so is a candidate for the “voltage” of circuit analysis.

However, circuit analysis also assumes particular expressions for the “voltage drop” across particular circuit elements, which are only approximately equal to the difference in the Lorenz-gauge electric scalar potential between the ends of the element. That is, “voltage drops” in circuit analysis are neither exactly $\mathcal{E}\mathcal{M}\mathcal{F}$’s nor differences in a scalar potential function, with the discrepancies being of similar size in both cases. In general practice, it is equally accurate (or equally inaccurate) to characterize “voltage” in the analysis of “ordinary” circuits (defined in sec. 1) as related either to $\mathcal{E}\mathcal{M}\mathcal{F}$’s or to an electric scalar potential (in either to Lorentz or Coulomb gauges, as these are identical for “ordinary” circuits).

We now give examples for several types of circuit elements, assuming that the “voltage” and currents have time dependence $e^{j\omega t}$ where $j = -\sqrt{-1} = -i$.

### 3.2.1 Inductors

We begin with consideration of inductors, coils of wire for which effects of inductance are more prominent than those of resistance and capacitance.

Recall that (self) inductance is a geometric property of a loop (which is independent of time if the shape of the circuit is fixed),

$$L = \frac{\mu_0}{4\pi} \oint \oint \frac{dl \cdot dl'}{R}$$  \hspace{1cm} (17)

where $R$ is the distance between line elements $dl$ and $dl'$. Every loop in a circuit has an inductance, which is ignored in “ordinary” circuit analysis unless the loop contains an “inductor.”

Furthermore, the $\mathcal{E}\mathcal{M}\mathcal{F}$ associated with a loop is given by

$$\mathcal{E}\mathcal{M}\mathcal{F}_{\text{loop}} = \oint_{\text{loop}} E \cdot dl = -\frac{d\Phi_M}{dt} = -\frac{d}{dt} \oint_{\text{loop}} A \cdot dl,$$  \hspace{1cm} (18)

where

$$\Phi_M = \int_{\text{loop}} B \cdot d\text{Area} = \oint_{\text{loop}} A \cdot dl$$  \hspace{1cm} (19)

is the magnetic flux due to the current $I$ that passes through the loop.

The usual approximation in “ordinary” circuit analysis is to ignore effects of retardation and write

$$A(r, t) \approx \frac{\mu_0}{4\pi} \oint \frac{I(r',t)}{R} dl' \approx \frac{\mu_0 I(t)}{4\pi} \oint_{\text{loop}} \frac{dl'}{R},$$  \hspace{1cm} (20)

where we also ignore possible variation of the current around the loop of the circuit. Then, the magnetic flux (19) can be written

$$\Phi_M \approx \frac{\mu_0 I(t)}{4\pi} \oint \oint \frac{dl \cdot dl'}{R} = LI(t),$$  \hspace{1cm} (21)
That region, say from points 1 to 2 on the conductor, is often identified as the inductor in the circuit, and the inductance \( L \) with a fractional error of order 1 so that most of the integral outside the nominal coil. Then, along the axis of the coil, between points 1 and 2, we have largely azimuthal, with a small axial component primarily due to the current in the circuit if \( N \) is large. In this case, the magnetic field inside the coil is axial, and its vector potential is "inductive voltage drop" of that compact portion of the circuit, rather than of the circuit as a whole. Then, the \( \text{EMF} \) around the loop is (mis)identified as a voltage difference between the two ends of the inductor, with the implication that a scalar potential \( V \) can account for the behavior of inductors, as assumed in applications of Kirchhoff’s voltage law to networks.\(^{14}\)

However, the error is slight for a typical inductor in the form of a coil of \( N \) turns, where \( N \) is large. In this case, the magnetic field inside the coil is axial, and its vector potential is largely azimuthal, with a small axial component primarily due to the current in the circuit outside the nominal coil. Then, along the axis of the coil, between points 1 and 2, we have that \( \mathbf{E} \approx -\nabla V \), such that \( V_1 - V_2 \approx \int_1^2 \mathbf{E} \cdot d\mathbf{l} \), where now the line integral is not taken along the conductor of the coil, but along a line down its interior. That is, the \( \text{EMF} \) along this path between the ends of the coil is very close to the voltage drop \( V_1 - V_2 \) between them, with a fractional error of order 1/\( N \).\(^{15}\)

\(^{14}\)The notion that the (self) inductance \( L \) of a loop can be considered as localized between the ends of an “inductor” that occupies only part of the loop is an aspect of the “lumped impedance” approximation. This is sometimes justified for inductance via energy considerations, perhaps following the lead of chap. VII of Maxwell’s *Treatise* [34]. The most extensive discussion may be that by Heaviside, art. 25, sec. 4, art. 27, sec. 5a and art. 28, secs. 1-9 of [35]. See also sec. 5.4 of [36]. The energy stored in the magnetic field (and in the magnetization, if any) of an “ordinary” circuit that carries current \( I \) can be written as

\[
U_M = \int_{\text{all space}} \frac{\mathbf{B} \cdot \mathbf{H}}{2} d\text{Vol} \approx \int_{\text{inductor}} \frac{\mathbf{B} \cdot \mathbf{H}}{2} d\text{Vol} \approx \frac{L_{\text{inductor}} I^2}{2}. \tag{24}
\]

Furthermore,

\[
U_M = \int \frac{\mathbf{H} \cdot \nabla \times \mathbf{A}}{2} d\text{Vol} \approx \int \frac{\mathbf{A} \cdot \nabla \times \mathbf{H}}{2} d\text{Vol} = \int \frac{\mathbf{A} \cdot (\mathbf{J} + \partial \mathbf{D}/\partial t)}{2} d\text{Vol} \approx \int \frac{\mathbf{A} \cdot \mathbf{J}}{2} d\text{Vol} \approx \frac{\int_{\text{inductor}} \mathbf{A} \cdot d\mathbf{l}}{2} = \frac{I \Phi_{M,\text{total}}}{2} = \frac{L_{\text{inductor}} I^2}{2}, \tag{25}
\]

where the first approximation requires the neglect of the surface integral at infinity, \( \int \mathbf{A} \cdot \mathbf{H} d\text{Area} \), that arises in the integration by parts, which integral is nonzero in general due to radiation; the second approximation requires the neglect of the “displacement current” \( \partial \mathbf{D}/\partial t \); and the fourth approximation (like that used in eq. (24)) supposes that most of the magnetic flux through the circuit is localized in the “inductor.”

\(^{15}\)Another option is to consider a path between points 1 and 2 that lies entirely outside the coil, along which \( V_1 - V_2 \approx \int_1^2 \mathbf{E} \cdot d\mathbf{l} \) is also valid. See, for example, chap. 22 of [10].
The geometry of a coil permits us to consider the EMF between its ends along a path that does not follow the helical winding, but runs straight through “empty” space between the end points. As discussed in sec. 3.2.3 below, if the coil is made from a perfect conductor, the EMF between its endpoints, evaluated along the path of that conductor, is zero. However, the dependence on the path of the EMF in time-dependent situations can be exploited to redefine the EMF associated with a coil to equal approximately the total EMF around the circuit, and also approximately equal the difference in the electric scalar potential between the ends of the coil.

3.2.2 AC Voltage Source

As discussed above in sec. 3.1.2, an AC voltage source (regulated by an internal voltmeter) delivers a fixed EMF to the extent that time-varying magnetic fields have negligible effect on the source. When such fields are negligible, the voltage source also delivers, to a good approximation, a fixed difference in the electric scalar potential (in the Lorenz gauge) between its terminals.

3.2.3 Perfectly Conducting Wires

Perhaps the simplest circuit element is a wire, often assumed to be perfectly conducting.

The electric field at the surface of a perfect conductor must have zero tangential component (and \( E = 0 \) inside the conductor), so the EMF is zero along any such wire. Hence,

\[
\text{EMF} = 0 = \int_1^2 E \cdot dl = V_1 - V_2 - \frac{d}{dt} \int_1^2 A \cdot dl \quad \text{(perfect conductor),} \tag{26}
\]

for any pair of points 1 and 2 on the perfect conductor. In general, the electric scalar potential is not constant over a perfect conductor,\(^{16}\)

\[
V_1 - V_2 = \frac{d}{dt} \int_1^2 A \cdot dl \quad \text{(perfect conductor).} \tag{27}
\]

The presence of the term in eq. (26) involving the vector potential \( A \) is a reminder that magnetic effects of a current-carrying wire should not be completely ignored, although the usual procedure in “ordinary” circuit analysis is to do so. Every loop in a circuit has an inductance that should, in principle, be accounted for in the circuit analysis.\(^{17}\)

To get a sense of the size of the error made in ignoring this inductance for loops without an “inductor,” we consider a loop of radius \( a \) made of a perfectly conducting wire of radius \( r_0 \). When that wire carries current \( I \) the magnetic field close to the wire circulates around it, and varies with distance \( r \) from the center of the wire as

\[
B \approx \frac{\mu_0 I}{2\pi r} . \tag{28}
\]

\(^{16}\)This fact is disconcerting to those who identify “voltage” with a static electric scalar potential, which has a constant value everywhere in/on a perfect conductor.

\(^{17}\)A complete, perfectly conducting loop must have \( \oint_{\text{loop}} E \cdot dl = 0 \), so the magnetic flux \( \Phi_M \) through the loop cannot change with time. The practical realization of a perfect conductor is a superconductor – which will cease to be a superconductor (quench) if the magnetic flux through a superconducting loop is force to change.
The magnetic flux linked by the loop of radius \(a\) is approximately

\[
\Phi_M \approx 2\pi a \int_{r_0}^a B \, dr = \mu_0 a I \ln \frac{a}{r_0}. \tag{29}
\]

Recalling eq. (21), we estimate the (self) inductance of the wire loop as

\[
L = \frac{\Phi_M}{I} \approx \mu_0 a \ln \frac{a}{r_0}. \tag{30}
\]

The wire has length \(2\pi a\), so the inductance per unit length of the wire is

\[
\frac{\mu_0}{2\pi} \ln \frac{a}{r_0} \approx \mu_0 \approx 10^{-6} \text{ H/m} = 10 \text{ nH/cm} \quad \text{(inductance per length of a wire).} \tag{31}
\]

### 3.2.4 Resistive Wires

A wire of radius \(r\) and length \(l\) has resistance

\[
R = \frac{l}{\pi r^2 \sigma} \tag{32}
\]

for axial current flow \(I = \pi r^2 J\). The current density \(J\) is related to the electric field inside the wire by

\[
J = \sigma E, \tag{33}
\]

where \(\sigma\) is the electrical conductivity of the wire. Then,

\[
IR = \frac{Jl}{\sigma} = EL = \Delta V_{\text{resistor}} - l \frac{\partial A}{\partial t}. \tag{34}
\]

As noted in sec. 3.2.3, a (resistive) wire loop is associated with a small self inductance (31) which should be included in the circuit analysis if accuracy is desired.

### 3.2.5 Capacitors

If the circuit includes a capacitor of value \(C\), then the \(\mathcal{EMF}\) across the capacitor is \(Q/C\) where \(Q(t)\) is the magnitude of the electric charge on one of the plates of the capacitor. For a typical capacitor the electric field between its electrodes has very little contribution from the vector potential, so that \(E \approx -\nabla V\), and the \(\mathcal{EMF}\) across the capacitor is very close to \(V_1 - V_2\), the difference in the scalar potential between the electrodes.

We have now verified, element by element, that the circuit analysis of a loop that contains a voltage source \(V\), and inductor \(L\), a resistor \(R\) and a capacitor \(C\), all in “series,” can be described by a set of “voltage drops” each of which is very close to the difference in the electric scalar potential (in the Lorenz gauge) between the ends of the element. The sum of these “voltage drops” around the loop is zero (Kirchhoff’s voltage law), which fact is usually summarized in the form

\[
V = LI + IR + \frac{Q}{C} = j\omega LI + IR - \frac{jI}{\omega C}, \tag{35}
\]

where the latter form holds when the voltage source is sinusoidal with angular frequency \(\omega\).\footnote{Kirchhoff’s “law” is not an exact law of physics, but rather is a useful approximation. The “voltage...}
3.3 Voltage and Transmission Lines

A transmission line is a pair of parallel, linear conductors, often approximated as perfect conductors, that support transverse electromagnetic (TEM) waves in the direction of the conductors.

The electric scalar potential provides a useful, “exact” description of the TEM waves on a transmission line (although most people are not aware of this). The scalar potential is defined everywhere, and can be written as a traveling wave,

\[ V(x, y, z, t) = V_{\perp}(x, y) e^{j(\omega t - kz)}, \tag{36} \]

where the z-axis is in the direction of the conductors, and \( \omega/k \) is the speed \( c \) of electromagnetic waves in the medium outside the conductors. Similarly, the electric and magnetic fields, which have no \( z \)-components for TEM waves, can be written

\[ E(x, y, z, t) = E_{\perp}(x, y) e^{j(\omega t - kz)}, \quad B(x, y, z, t) = B_{\perp}(x, y) e^{j(\omega t - kz)}, \tag{37} \]

and the vector potential can be written as

\[ A(x, y, z, t) = A_z(x, y) e^{j(\omega t - kz)} \hat{z}, \tag{38} \]

since the currents that generate the vector potential have only a \( z \)-component. As the electric field has no \( z \)-component, eq. (8) tells us that

\[ E_z = -\frac{\partial V}{\partial z} - \frac{\partial A_z}{\partial t} = jkV_{\perp}(x, y) e^{j(\omega t - kz)} + j\omega A_z e^{j(\omega t - kz)}, \tag{39} \]

and hence,\n
\[ A_z = \frac{k}{\omega} V_{\perp} = \frac{V_{\perp}}{c}. \tag{40} \]

Since \( B_z = 0 \), Faraday’s law tells us that

\[ 0 = -\frac{\partial B_z}{\partial t} = (\nabla \times E)_{\perp} = \nabla_{\perp} \times E_{\perp} e^{j(\omega t - kz)}, \tag{41} \]

where \( \nabla_{\perp} = (\partial/\partial x, \partial/\partial y) \). Hence, the 2-dimensional, time-independent field \( E_{\perp} \) has zero curl, and so can be deduced from a (static) 2-dimensional scalar potential \( V_{\perp} \) according to

\[ E_{\perp} = -\nabla_{\perp} V_{\perp}. \tag{42} \]

**drops** which appear in this “law” are not strictly \( \mathcal{E}\mathcal{M}\mathcal{F} \)'s along the conductors of the circuit, nor are they exactly equal to the differences in the electric scalar potential between the ends of the various circuit elements. In practice, there is very little error in identifying the “voltage drops” with either the \( \mathcal{E}\mathcal{M}\mathcal{F} \)'s or the differences in electric scalar potential. However, this useful approximation tends to leave many people without a crisp understanding of the difference between “voltage drop,” potential difference, and \( \mathcal{E}\mathcal{M}\mathcal{F} \), which can be large outside “ordinary” circuit analysis.

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In the approximation of perfect conductors, $E_\perp$ vanishes on the surfaces of the conductors of the transmission line, we recognize $V_\perp$ and $E_\perp$ as the electrostatic potential and static electric field that could be supported by the conductors of the transmission line.\(^{21}\)

The electric field can now be deduced from the potentials as

$$E = -\nabla V - \frac{\partial A}{\partial t} = -\nabla V_\perp e^{i(\omega t - k z)} + jk V_\perp e^{i(\omega t - k z)} \hat{z} - j\omega A_z e^{i(\omega t - k z)} \hat{z} = E_\perp e^{i(\omega t - k z)}.$$

Note that for two points, 1 and 2, with the same $z$-coordinate,

$$\mathcal{EMF}_{12} = \int_{1}^{2} E \cdot dl = -\int_{1}^{2} \nabla V_\perp e^{i(\omega t - k z)} \cdot dl = (V_{\perp,1} - V_{\perp,2}) e^{i(\omega t - k z)} = V_1 - V_2. \quad (44)$$

for any path in the plane of constant $z$. However, if points 1 and 2 have different $z$-coordinates the $\mathcal{EMF}_{12}$ depends on the path (because of the factor $e^{-jkz}$ in the integrand of eq. (44)).

Most discussions of transmission lines imply that the scalar potential is defined only on the conductors, and omit discussion of the potential in the space around them. Often, the potential difference between the two conductors at a given $z$ is related to a line integral of $E \cdot dl$ at fixed $z$, as in eq. (44), which can give the impression that the potential difference is also an $\mathcal{EMF}$, and perhaps that the potential is a static potential. That is, many discussions do not distinguish between the full scalar potential (wave) $V = V_\perp e^{i(\omega t - k z)}$ and its time-independent amplitude $V_\perp(x, y)$.

### 3.4 Voltage and Antennas

Antennas are conductors designed to guide the flow of electromagnetic energy from an energy source into electromagnetic waves that travel away from the antenna into the “empty” space surrounding it. The flow of energy is described by the Poynting vector

$$S = \mu_0 E \times B,$$  \(^{45}\)

and, in examples where the time dependence is purely sinusoidal, by its time average

$$\langle S \rangle = \frac{\mu_0}{2} Re(E \times B^*). \quad (46)$$

The energy source is usually characterized as a “voltage” source that delivers a known “voltage drop” across the “terminals” of the antenna. For example, if the source “voltage drop” is $V_{\text{source}}$ and the distance between the terminals is $d\hat{z}$, we suppose that the electric field along the line between the terminals is $E_{\text{source}} = V_{\text{source}} \hat{z}/d$.

Typical antenna analysis involves computation of the Poynting vector (i.e., the far-field radiation pattern $r^2 \langle S \rangle$, which is independent of $r$ at large $r$) from the fields $E$ and $B$, with these fields being computed from the retarded potentials $V$ and $A$,\(^{22}\) the potentials being

\(^{21}\)Further details for a coaxial transmission line are given in [37].

\(^{22}\)The behavior of the fields far from most antennas is well described in terms of their electric and magnetic dipole moments $\mathbf{p}$ and $\mathbf{m}$. The potentials in the far zone are then $V \approx jk \mathbf{p} \cdot \hat{r} e^{j(\omega t - kr)}/4\pi er$ and $A \approx j\omega \mu_0 (\mathbf{p} + \mathbf{m} \times \hat{r}) e^{j(\omega t - kr)}/4\pi r$. Both $\nabla V$ and $\partial A/\partial t$ have longitudinal components that vary as $1/r$ at large $r$, but $E = -\nabla V - \partial A/\partial t$ is purely transverse.
computed from the charge and current distributions, $\rho$ and $\mathbf{J}$, and these distributions being computed from the source voltage/field.\textsuperscript{23} These computations are simplified by use of the equation of continuity, $\nabla \cdot \mathbf{J} = -\partial \rho / \partial t$, and/or the Lorenz-gauge condition (11), to eliminate $\rho$ and/or $V$ in favor of $\mathbf{J}$ and/or $\mathbf{A}$.\textsuperscript{24}

Such computations are nontrivial, and are now mainly performed by Numerical Electromagnetic Codes, such as NEC4 [39] (for pure sinusoidal time dependence), which report the radiation pattern (i.e., the Poynting vector), the terminal impedance (ratio of terminal “voltage” to terminal current), and, if requested, the fields $\mathbf{E}$ and $\mathbf{B}$ close to the antenna. The potentials $V$ and $\mathbf{A}$ are not reported, which can give the impression that they are irrelevant, and perhaps even undefined.

Use of a voltmeter with an antenna system generally does not lead to results that are closely related to the scalar potential $V$ (or even to the $\mathbf{E}\mathbf{M}\mathbf{F}$ along the meter leads), and which are very dependent on the path of the leads of the voltmeter.\textsuperscript{25,26} If one considers that “voltage is what a voltmeter measures,” this behavior gives the impression that “voltage” is not well-defined near antennas. We take the attitude that it is better to consider “voltage” to be well-defined as the scalar potential $V$ in the Lorenz gauge, and to accept that a voltmeter measures this “voltage” reliably only in “ordinary” circuits.

**References**


On the Identity of the Vibrations of Light with Electrical Currents, Phil. Mag. 34, 287 (1867),


\textsuperscript{23}Antenna computations are examples of the electromagnetic fields throughout all space being deduced from partial information as to the fields in a very limited volume.

\textsuperscript{24}Sec. 11 of [38] is notable for its prominent use of both $V$ and $\mathbf{A}$ when discussing radiation.

\textsuperscript{25}See, for example, secs. 2.4-5 of [32].

\textsuperscript{26}A voltmeter whose leads are short compared to a wavelength, and not connected to anything, is a kind of receiving antenna whose open-circuit terminal voltage is the $\mathbf{E}\mathbf{M}\mathbf{F}$ $\mathbf{E} \cdot \mathbf{l}$ where $\mathbf{E}$ is the electric field of the antenna at the voltmeter and $\mathbf{l}$ is the (vector) length of the leads [40].


